

**Development of the deep learning-based modeling approaches
for nuclear reactor thermal-hydraulics applications**

Yue Jin

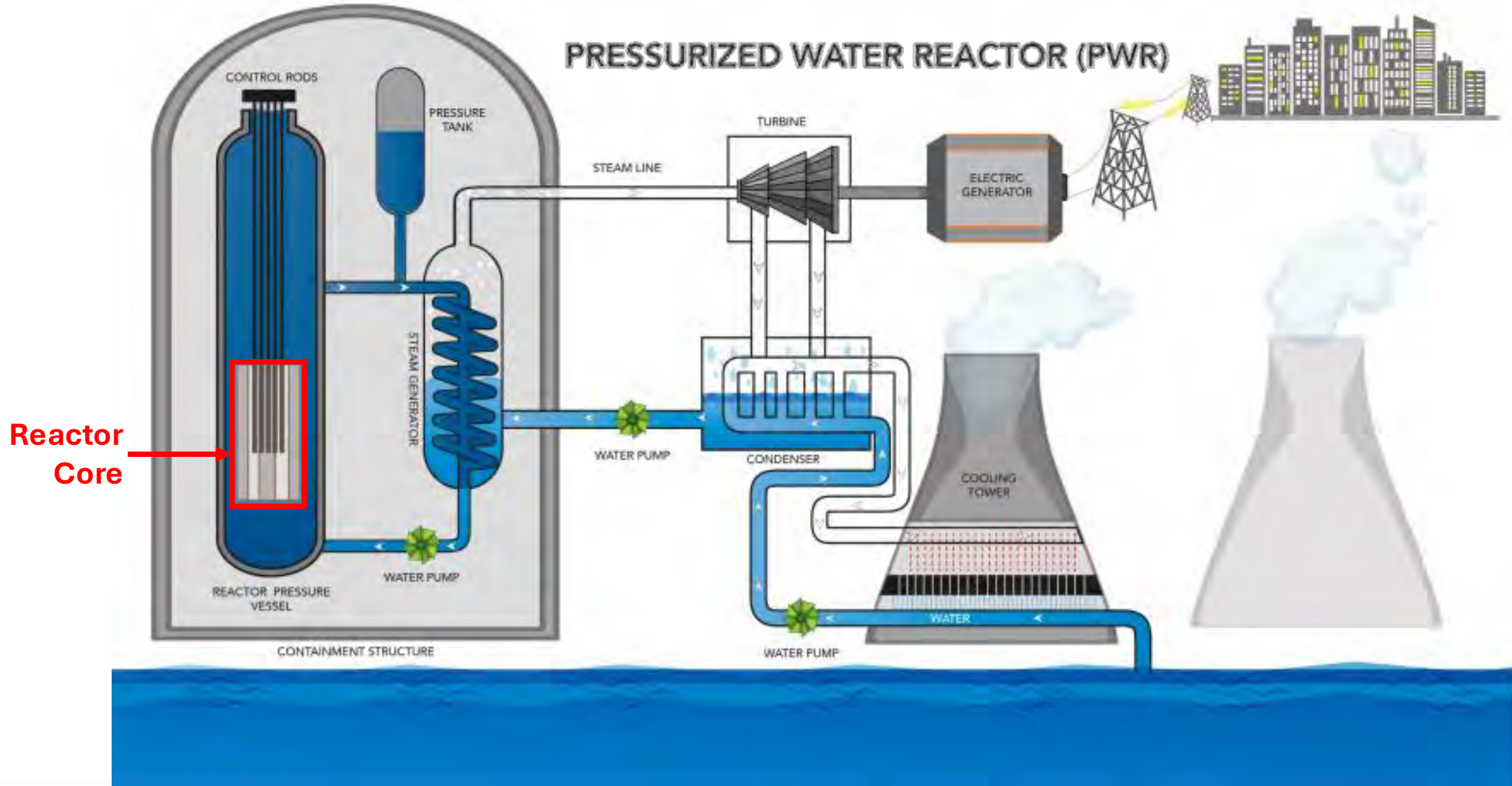
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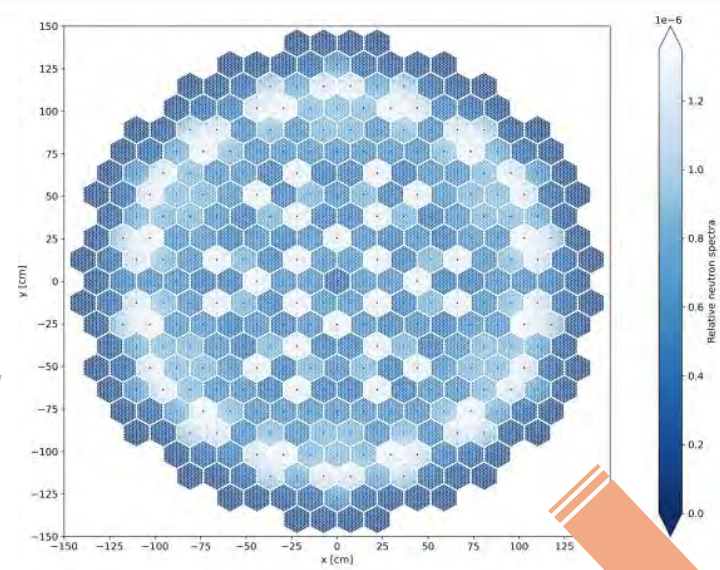
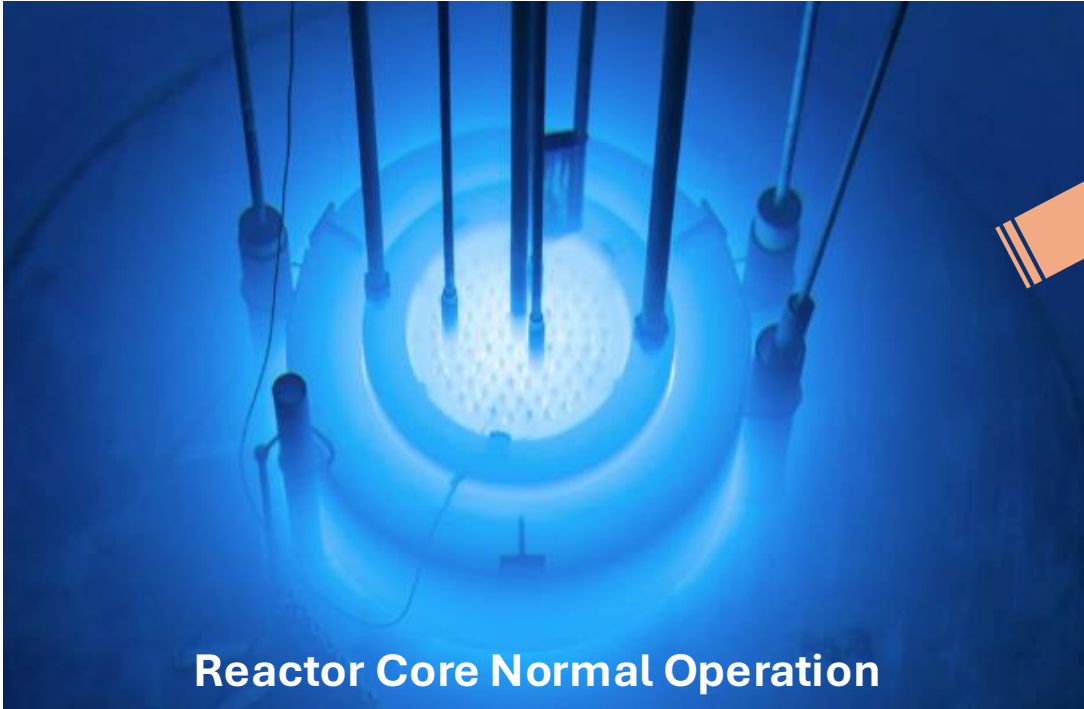
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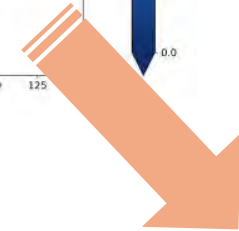
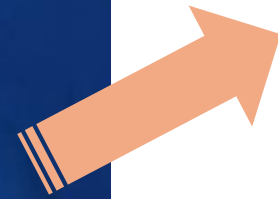
Nuclear Power Plant Operation



Reactor Core Fuel Assembly



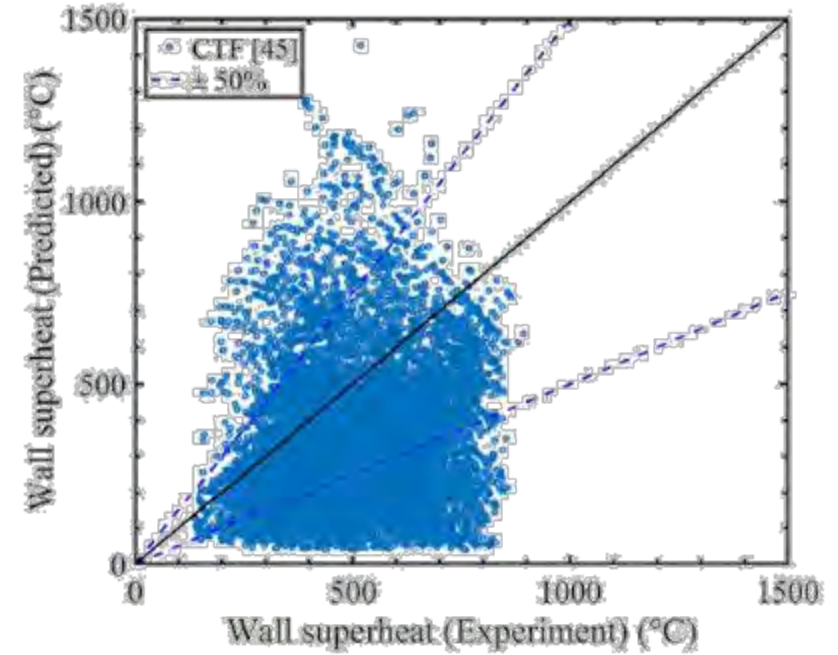
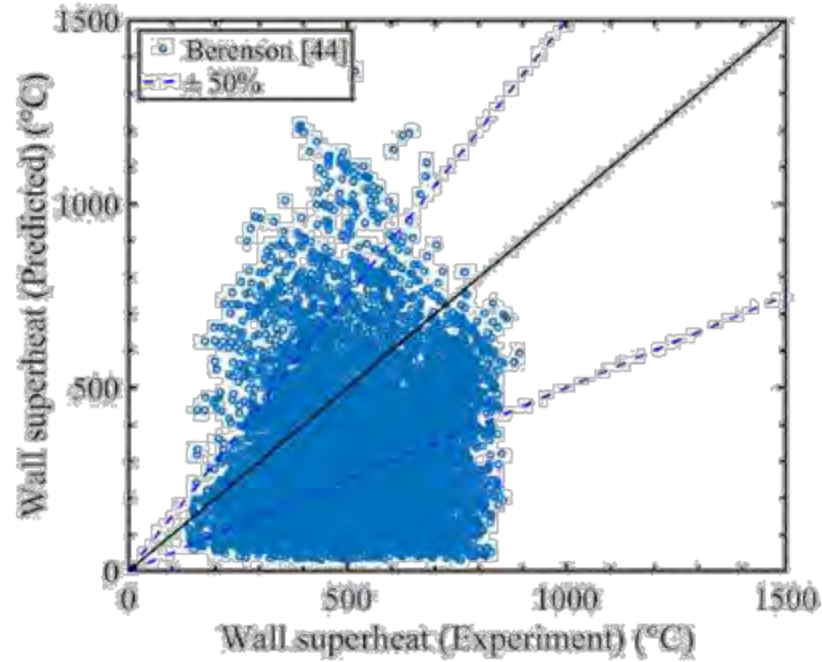
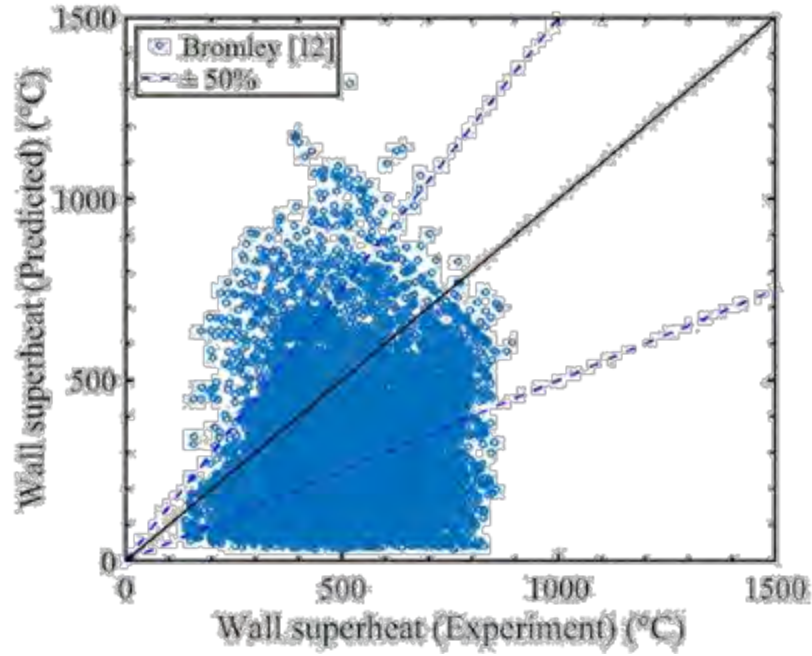
Nuclear Fuel Assembly Layout



Prevent **Boiling Crisis** and/or **Critical Heat Flux (CHF)** is the **KEY!**

Single Rod/Pin with Fuel Pellets

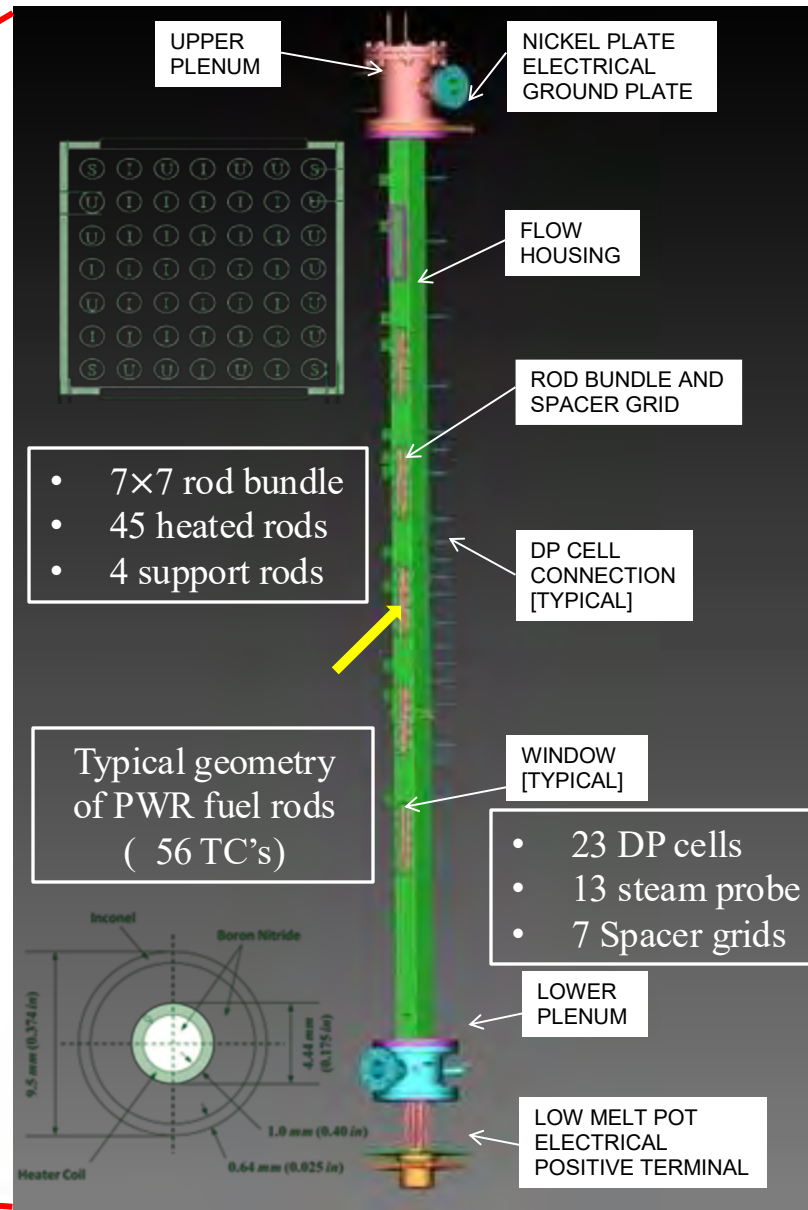
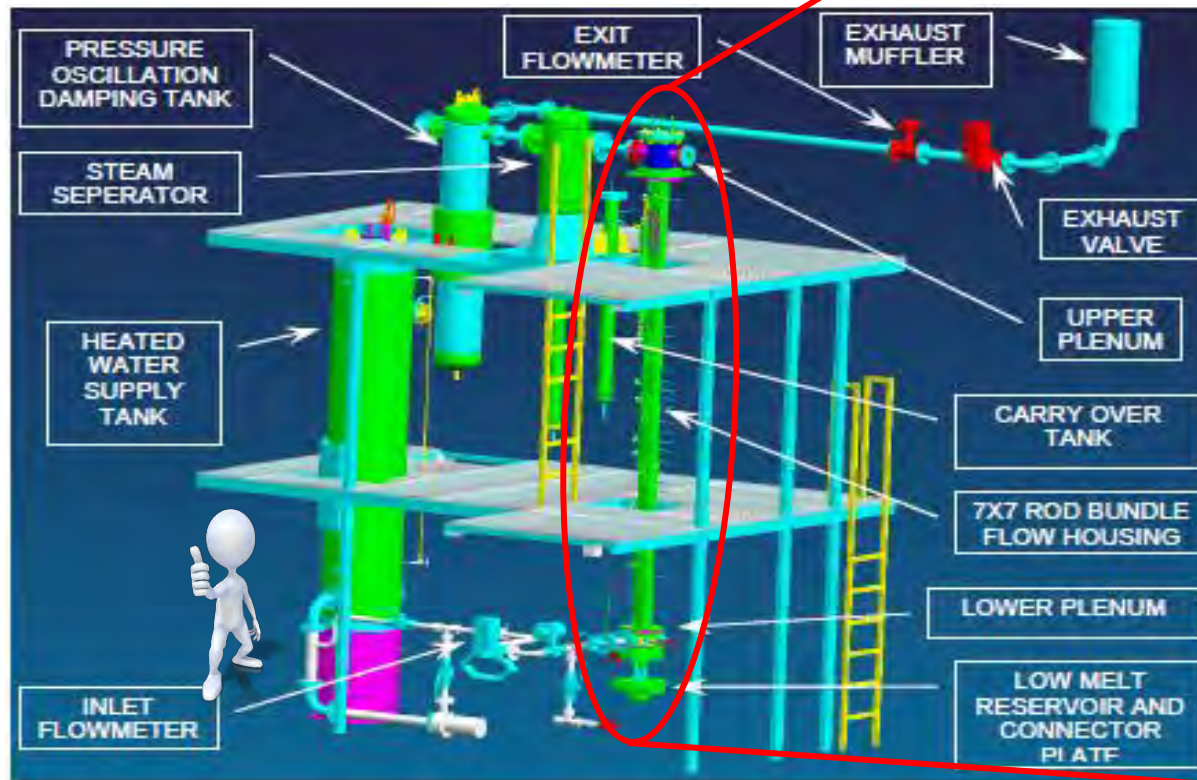
Original CHF Model Predictions



NRC/PSU Rod Bundle Heat Transfer (RBHT) Test Facility

- **System operating pressure:** up to 413.7 kPa (60 Psia)
- **Inlet water velocity:** -0.2 to 0.2 m/sec (-8 to 8 in/sec)
- **Peak power:** up to 1.97 kW/m (0.6 kW/ft)
- **Peak cladding temperature:** up to 1144.3 K (1600 °F)
- **Inlet subcooling:** up to 83 K (150 °F)

*Working fluid:
Water or Steam*

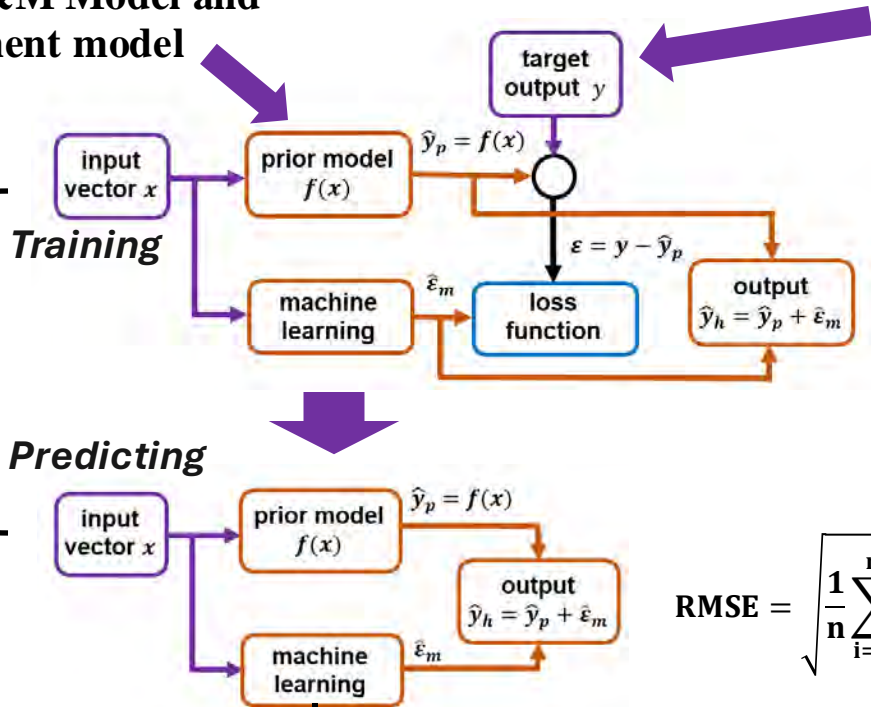


Physics Informed ML Structures

Standalone I&M Model and pool entrainment model

ML input space, x ,

- Pressure
- Inlet mass flow rate
- Rod temperature
- Fluid density
- Viscosity



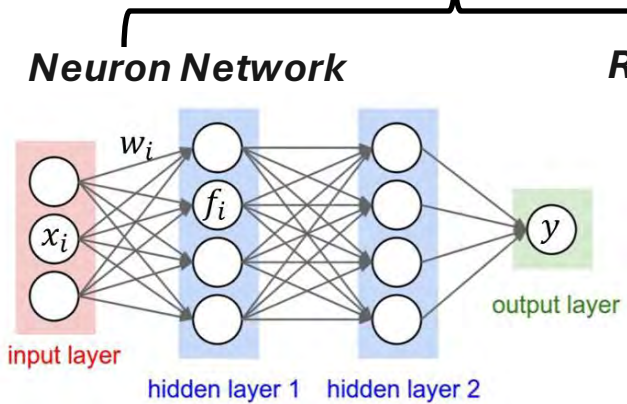
Exp #	Inlet Velocity m/s (in/s)	Pressure kPa (psia)	Initial PCT K (°F)	Subcooling K (°F)	Peak Power kW/m (kW/ft)	
7063	0.0254 (1)	275.8 (40)	1033 (1400)	10 (18)	1.31 (0.4)	
7090	0.0254 (1)			10 (18)	1.31 (0.4)	
7095	0.0254 (1)			80 (150)	1.31 (0.4)	
7112	0.0254 (1)			50 (90)	0.97 (0.3)	
7151	0.0191 (0.75)			53 (96)	1.31 (0.4)	
7157	0.0254 (1)			11 (20)	1.31 (0.4)	
7166	0.0254 (1)			80 (150)	1.31 (0.4)	
7168	0.0254 (1)			51 (91)	0.97 (0.3)	
7174	0.0191 (0.75)			53 (96)	1.31 (0.4)	
8009	0.0254 (1)			22.2 (40)	1.31 (0.4)	
8011	0.0254 (1)			53.3 (96)	1.31 (0.4)	
8018	0.0254 (1)			53.3 (96)	1.31 (0.4)	
8021	0.0254 (1)			137.9 (20)	22.2 (40)	1.31 (0.4)
8023	0.0254 (1)			413.7 (60)	22.2 (40)	1.31 (0.4)
8040	0.058 (2)	275.8 (40)	53.3 (96)	1.31 (0.4)		
8041	0.0254 (1)	206.8 (30)	22.2 (40)	1.31 (0.4)		

Total 10,047 data points

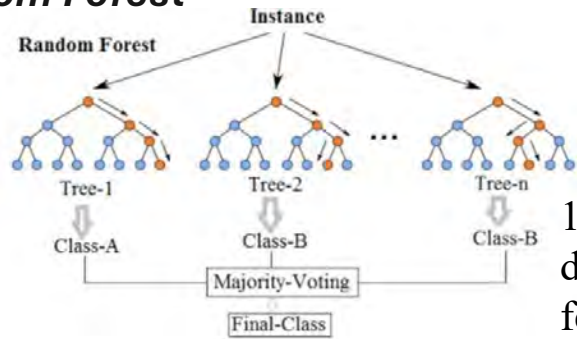
- 80% training and 20% validation
- Optimal ML architectures obtained through a comprehensive grid search study
- Early stop to prevent over training
- 10-fold cross-validation to address model over-fitting

$$RMSE = \sqrt{\frac{1}{n} \sum_{i=1}^n \left(\frac{y_{pred,i} - y_{exp,i}}{y_{exp,i}} \right)^2}$$

ANN architecture: 32/64/32/1 with “ADAM” optimizer, epoch of 90, and batch size of 350.

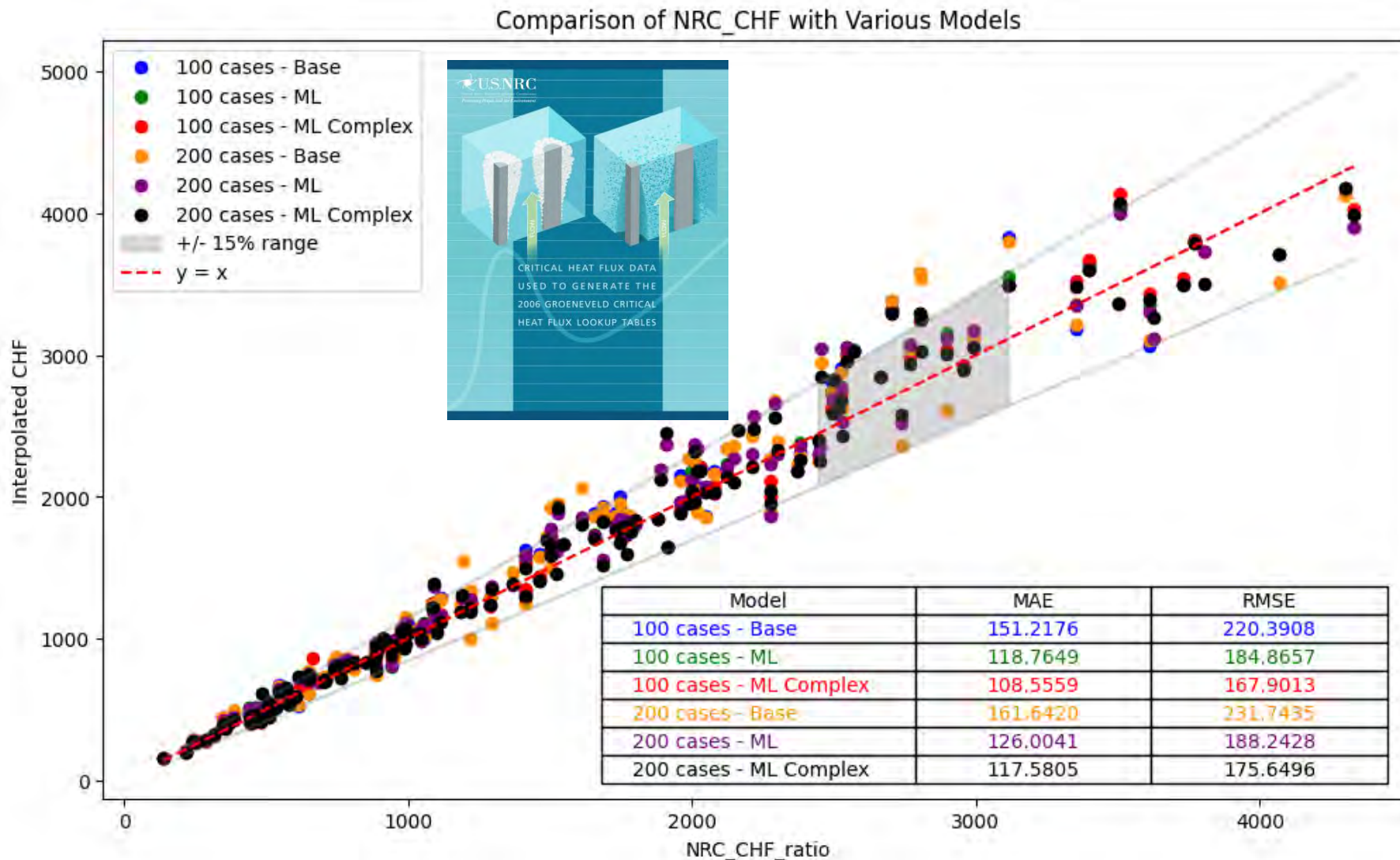
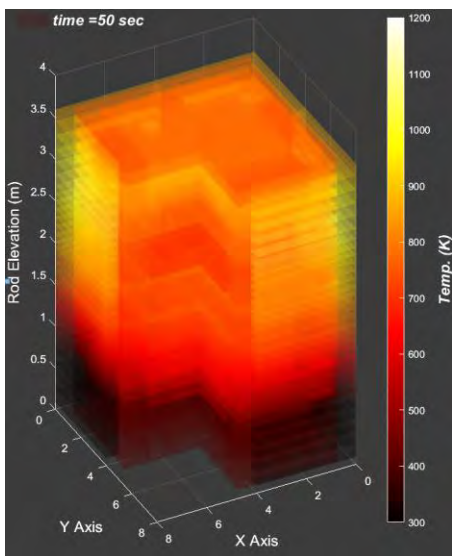
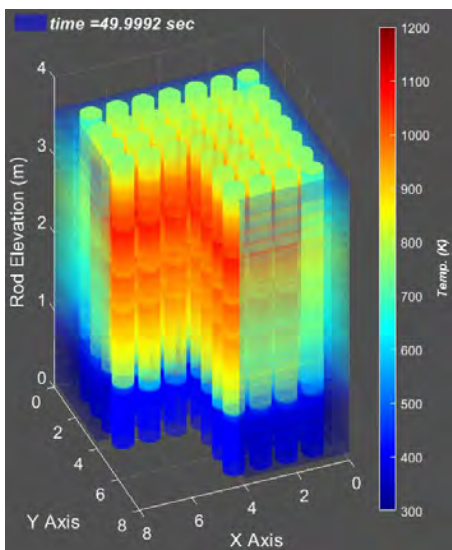


Random Forest



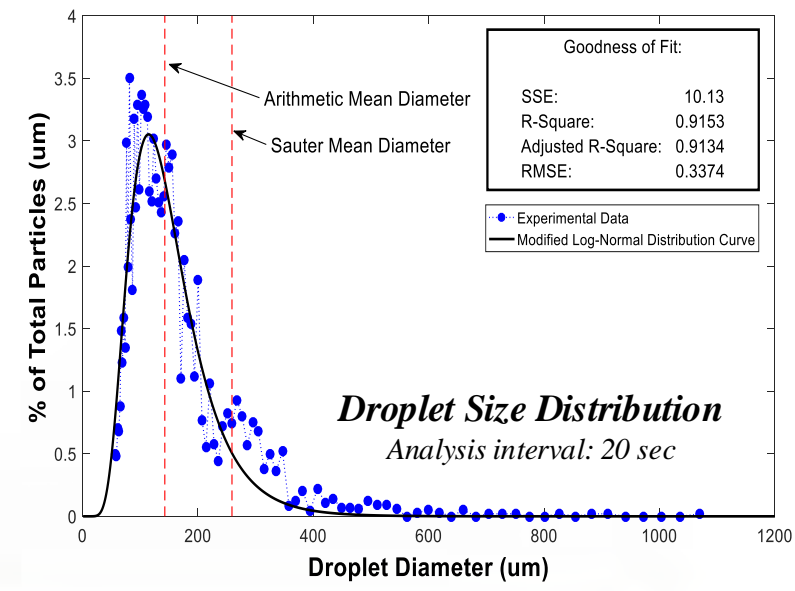
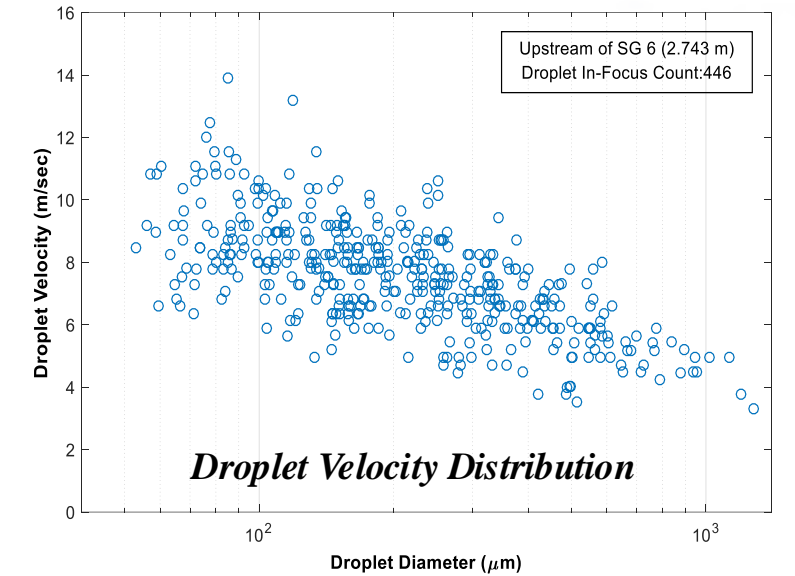
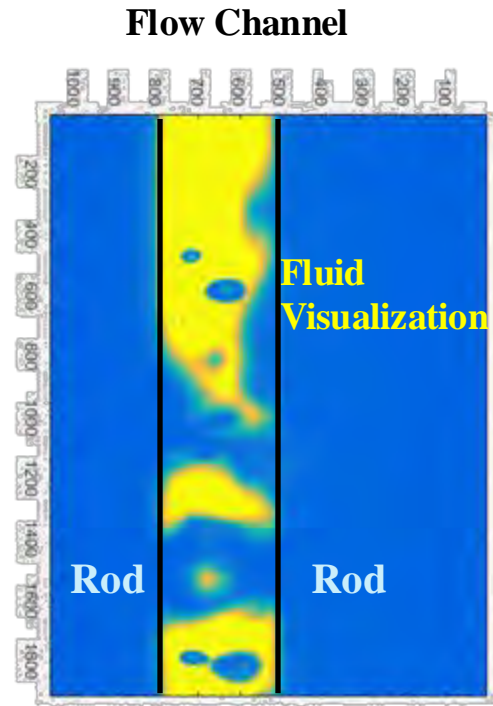
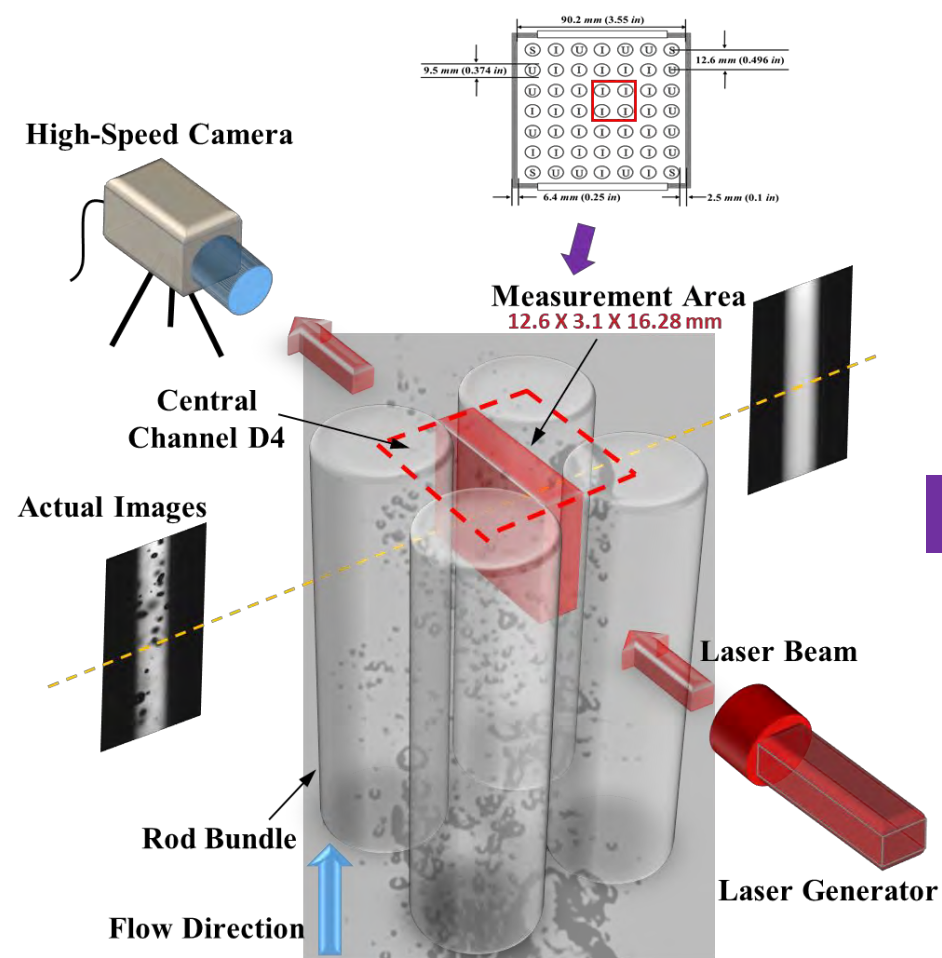
160 estimators with max depth of 35 and max feature of 0.6

ML CHF Model Predictions – Preliminary

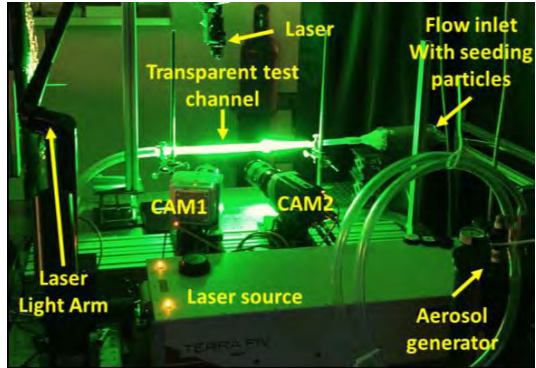


Benchmark Experiments

Laser Imaging System

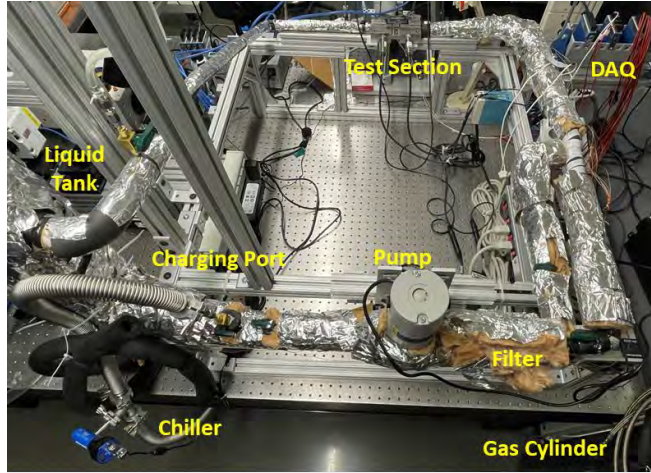


ML CHF Model Predictions – Preliminary

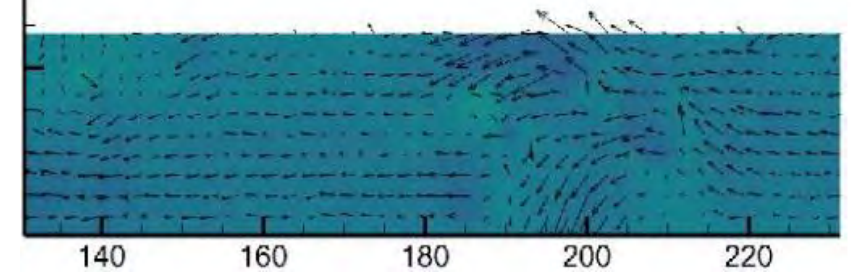
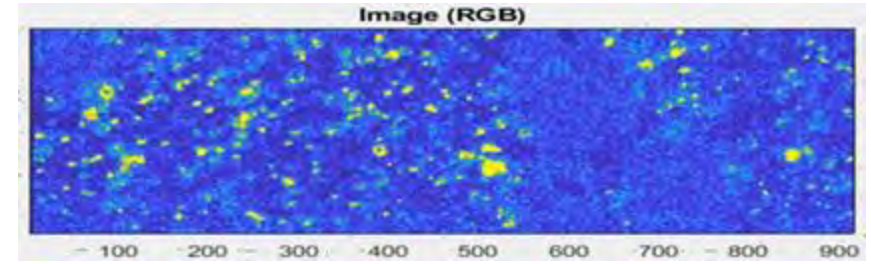


Macro-Scale Stereo-PIV

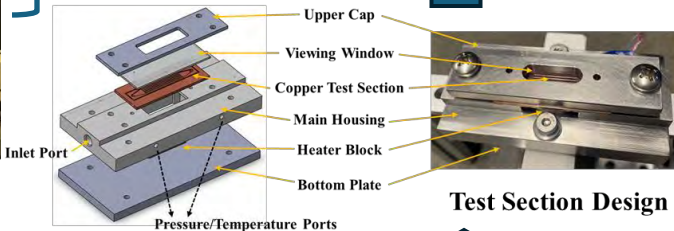
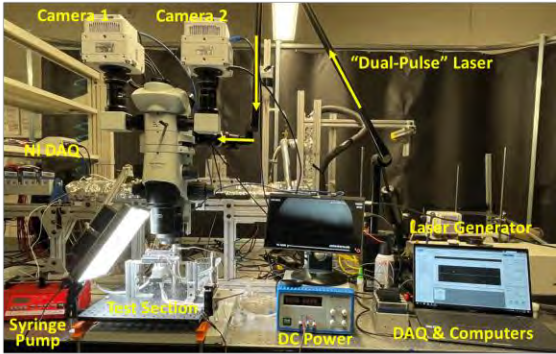
Flow and Heat Transfer Loop



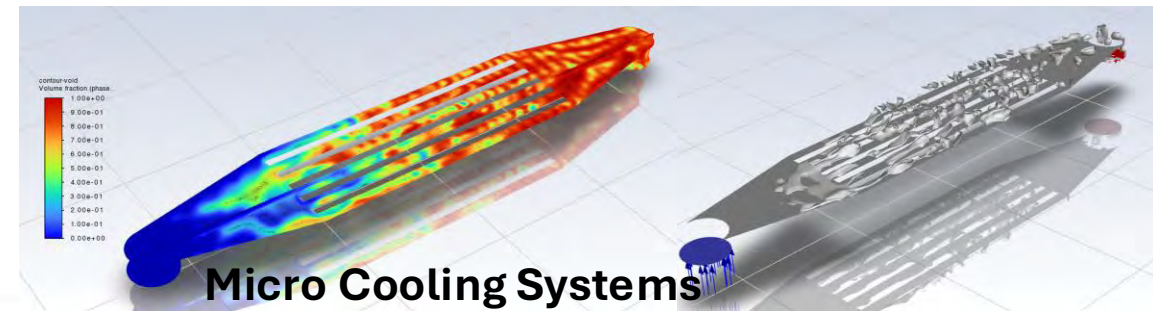
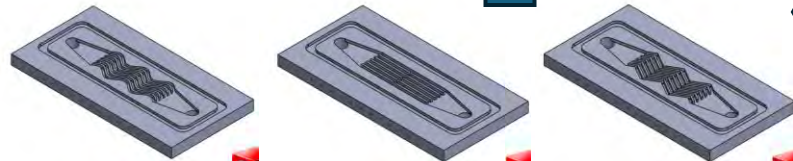
Velocity Profile in Microchannel



Micro-Scale Stereo-PIV

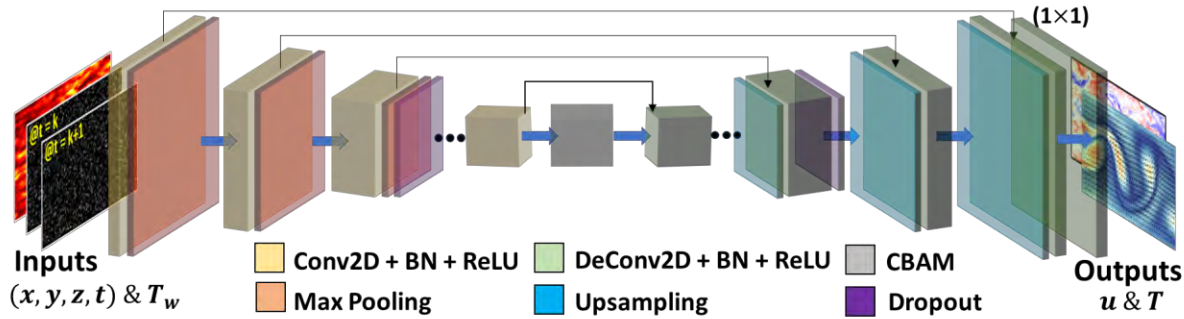


Test Section Design



Micro Cooling Systems

Computer Vision Aided Image Processing Techniques

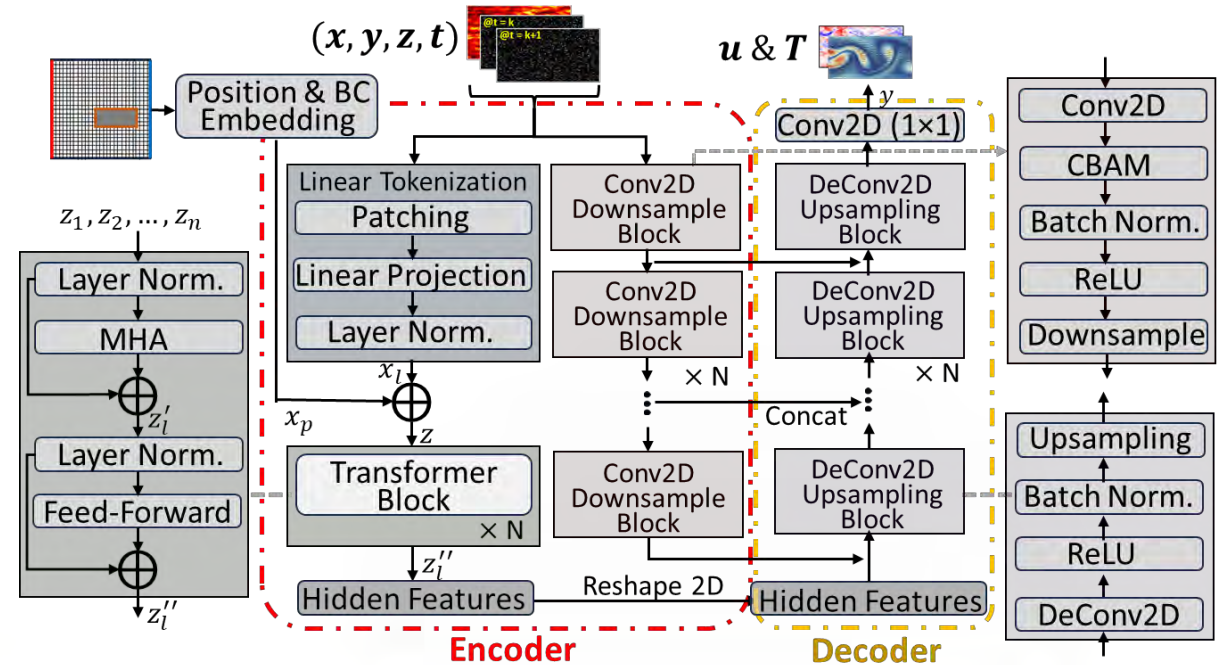


Fully Convolutional Neural Network (FCN) - Convolutional Block Attention Module (CBAM)

- Downsampling block consists of a convolution layer (Cov2D), batch normalization (BN), activation function, and max pooling layer
- Upsampling block restores the feature domain through deconvolution layers (DeCov2D)

Vision Transformer (ViT) based Model

- Encoder: linear tokenization block combined with both the position and known boundary conditions Transformer blocks with a multi-head self-attention (MHA) followed by a feed-forward neural network also with residual connections.
- Decoder: identical number of upsampling blocks



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Thanks

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